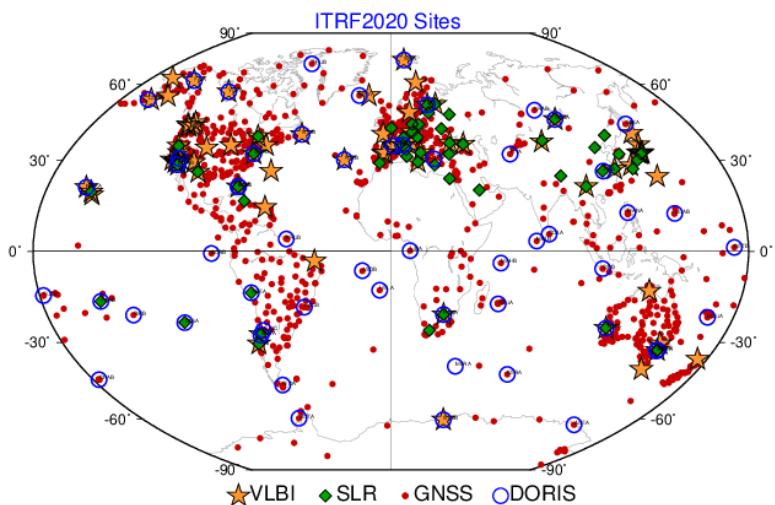
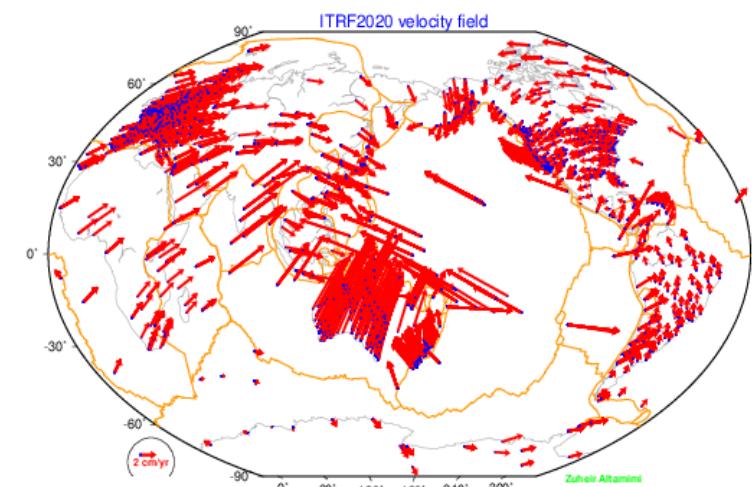


ITRF2020, son usage et perspectives



Zuheir Altamimi
Paul Rebischung
Maylis de La Serve
Xavier Collilieux
Laurent Métivier
Kristel Chanard

IGN-IPGP, France

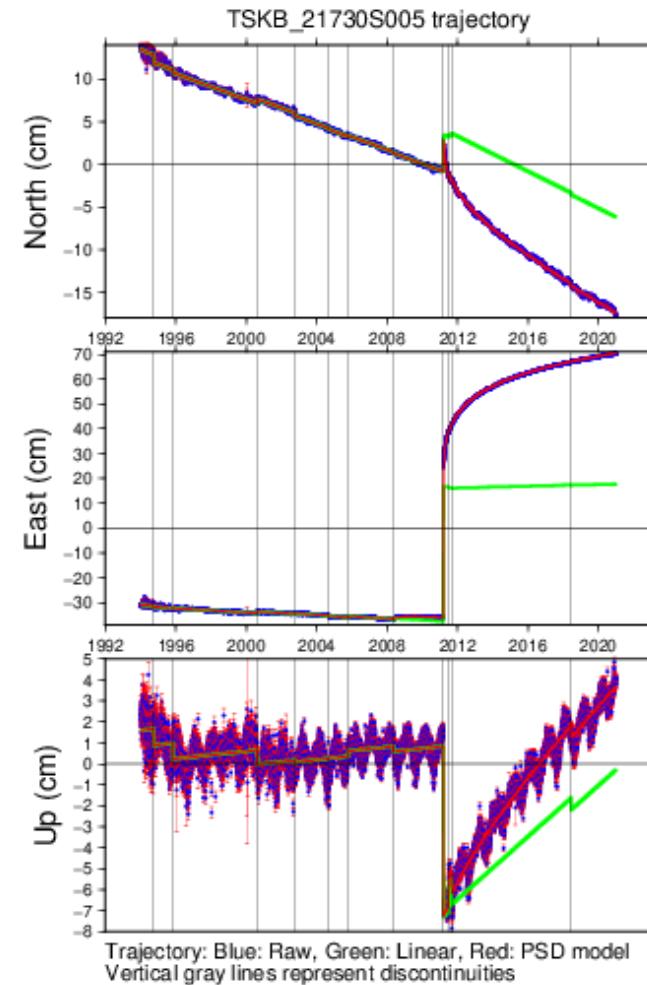


Outline

- **Introduction**
- **Reference frame representations and:**
 - The reality of a deformable Earth
 - Technique systematic errors
 - User needs
- **ITRF2020:**
 - Innovation: modeling of nonlinear station motions : seasonal signals & post-seismic deformation
 - ITRF2020 kinematic model and its usage
- **Perspectives**

“Motions” of the deformable Earth

- **Nearly linear motion:**
 - Tectonic motion
 - Post-Glacial Rebound
- **Nonlinear motion:**
 - Loading deformation, due to atmospheric pressure, hydrology and ocean circulation
 - Co- & Post-seismic deformations,
 - Transient deformations, Volcano Eruptions, local events...



Reference Frame Representations

- **Long-Term Linear Frame:** mean station positions at a reference epoch (t_0) and station velocities:

$$X(t) = X(t_0) + \dot{X}(t - t_0)$$

=> Regularized Position
With piece-wise linear function

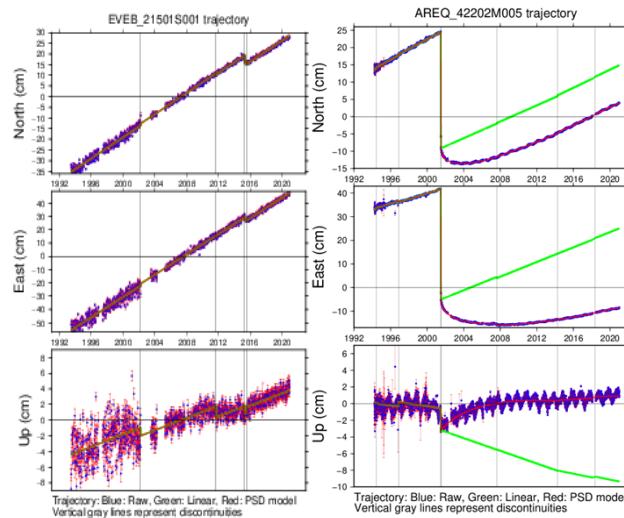
- The indispensable basis for science and operational geodesy applications
- **Nonlinear Reference Frames:**
 - Augmented Parametric RF: Long-Term Frame + nonlinear parametric functions (==> ITRF2020):

$$X(t) = X(t_0) + \dot{X} \cdot (t - t_0) + \delta X_{PSD}(t) + \delta X_f(t)$$

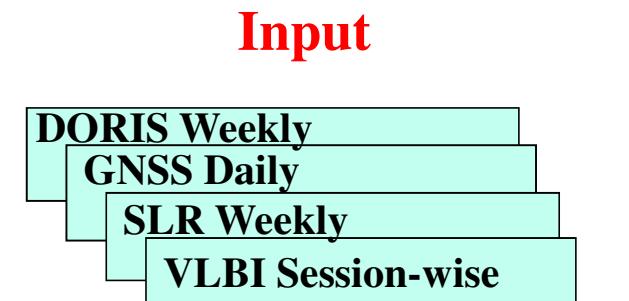
- **Non-parametric RF:** Time series of "Quasi-Instantaneous" reference frames
 - Daily or weekly representations
 - Nonlinear motion embedded in their time series
 - Still rely on the ITRF for at least the orientation definition

The International Terrestrial Reference Frame (ITRF):

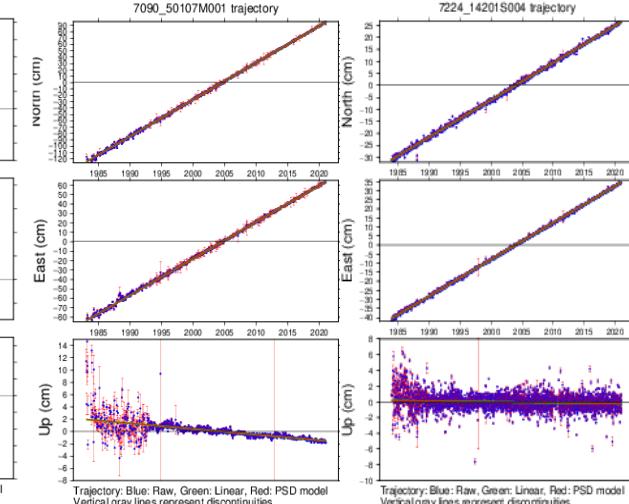
- Realized and maintained by the ITRF Center hosted by IGN
- By combination of DORIS, GNSS, SLR and VLBI station position time series



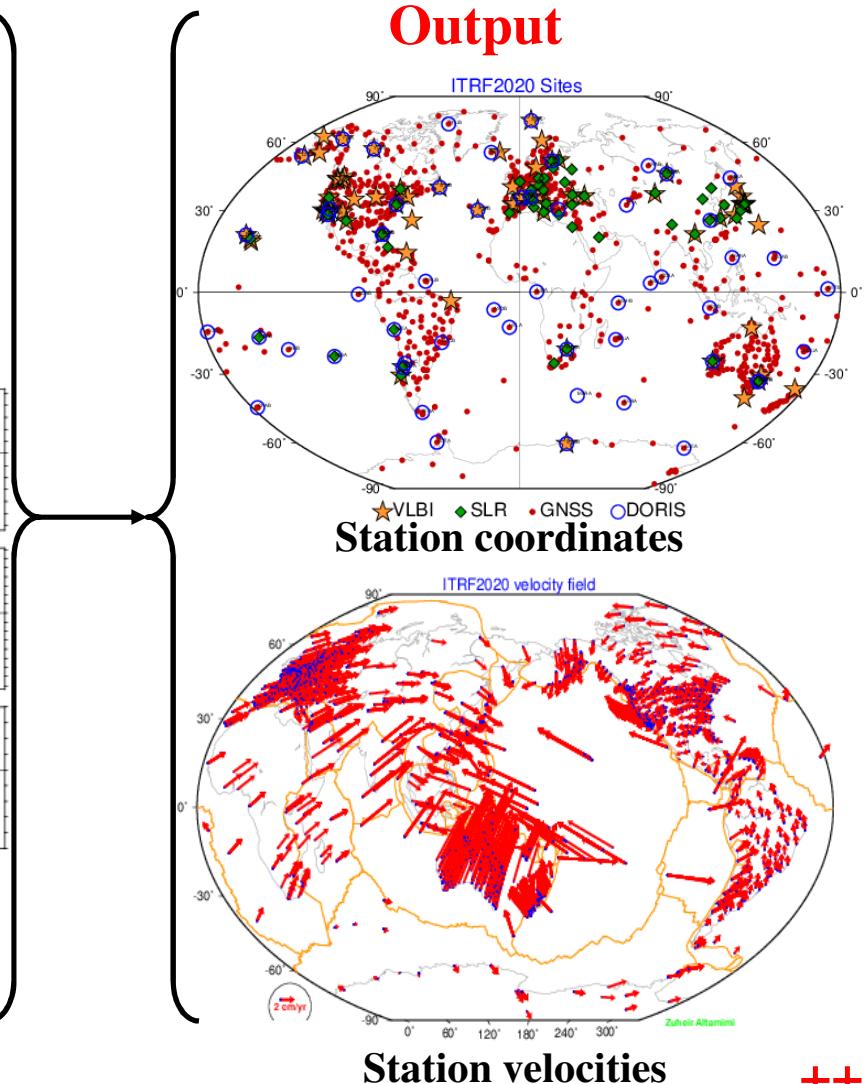
Fundamentally based on
Co-location Sites



Input



Time series analysis & stacking
(CATREF Software)



++

Why is the ITRF needed?

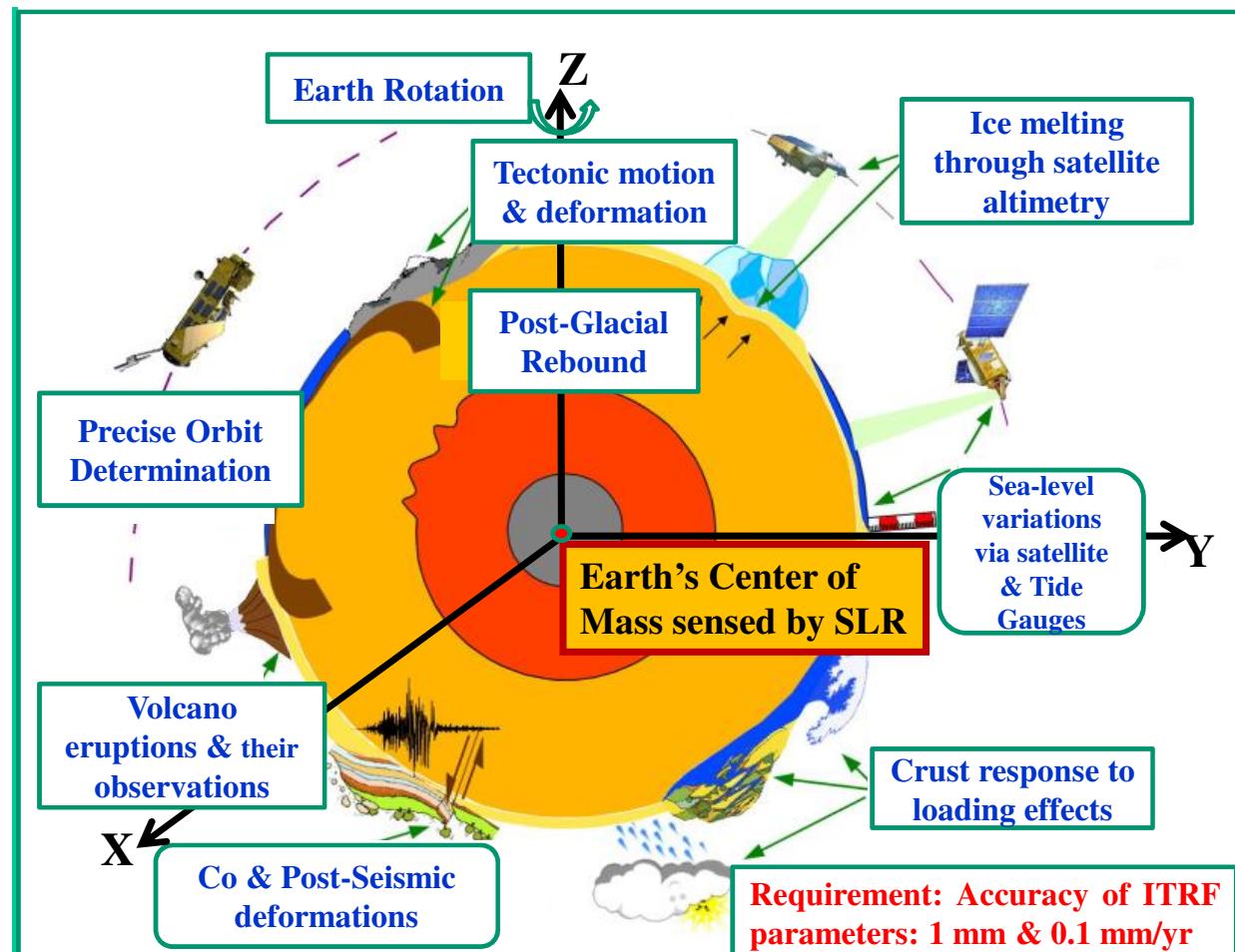
Operational geodesy applications:

- Positioning : Real Time or a posteriori
- Navigation: Aviation, Terrestrial, Maritime
- National geodetic systems/frames
- Today: via GNSS only!
- Require the availability of the orbits and the reference frame (ITRF)
- Many, many users...

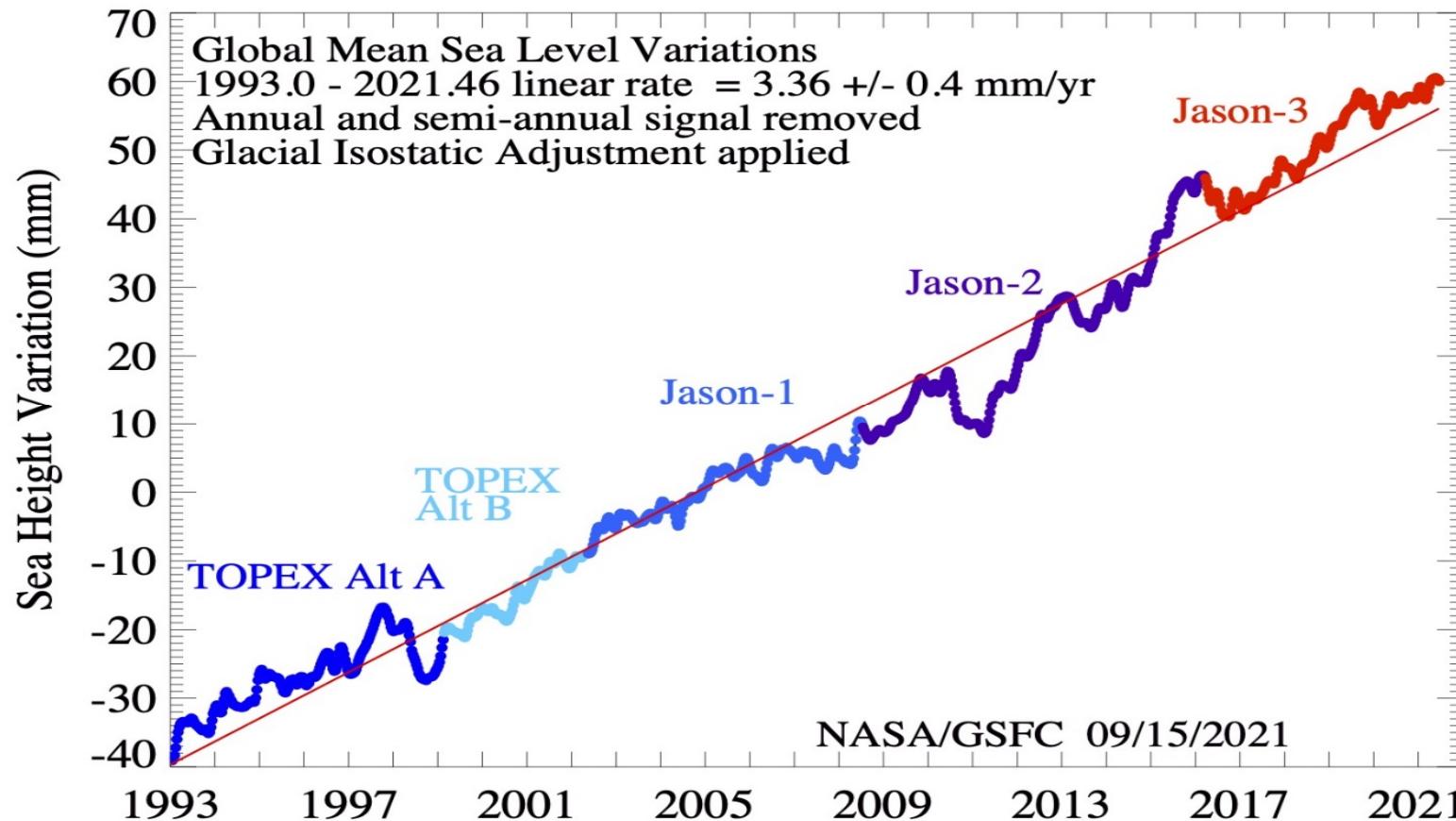
GNSS-specific reference frames:

- GTRF/Galileo, WGS84/GPS, PZ-90/GLONASS, CGCS2000/Beidou, JGS/QZSS
- All are aligned to the ITRF

Scientific Applications:



Mean sea level change



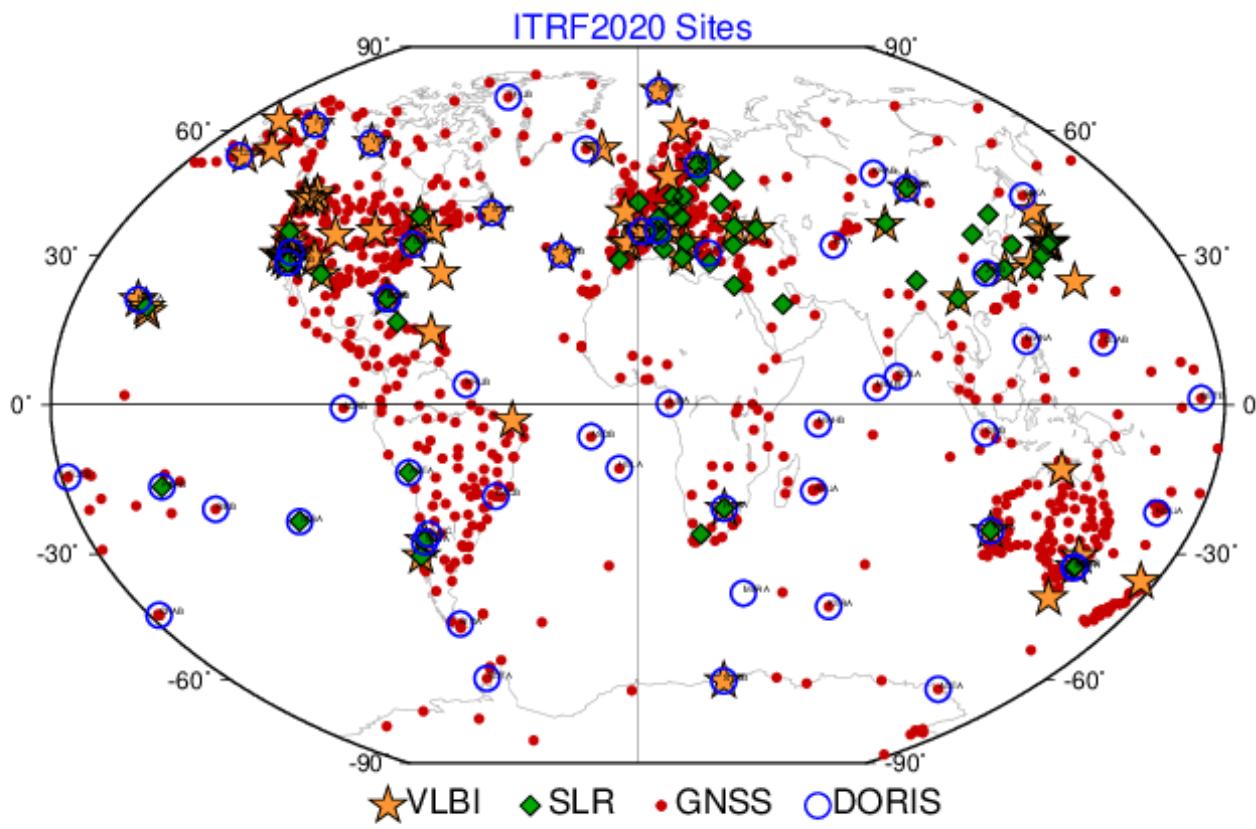
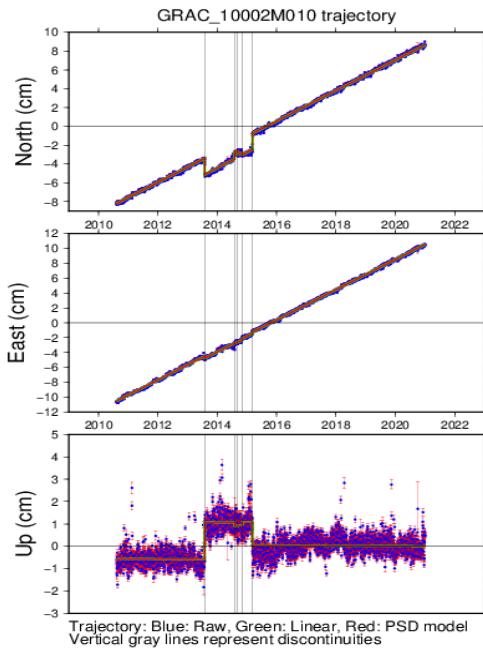
A small drift of 1 mm/yr in the ITRF origin, translates into an apparent 0.9 mm/yr sea level rise at high latitudes, via the POD

Resolutions on ITRS & ITRF

- **IUGG2007:** adopted the **ITRS** as the preferred Geocentric Terrestrial Reference System (GTRS) for scientific and technical applications
- **CGPM2011:** recommends that the **ITRS**, as defined by the IUGG and realized by IERS, be adopted as the unique international reference system for terrestrial reference frames for all metrological applications
- **ICG2012:** recommendation to align GNSS-specific reference frames (WGS84, PZ90, GTRF, CGCS2000, JGS) to the ITRF
- **IUGG2019:** recommend to the user community that the **ITRF** be the standard for positioning, satellite navigation and Earth Science applications, ...
- **UN-GGIM-2019:** adoption of the **ITRS** and the **ITRF** as the standard for scientific, geospatial and operational geodetic applications
- **ISO Standard on ITRS/ITRF**

ITRF2020 Network

- 1223 sites
 - 878 Northern hemisphere
 - 355 Southern hemisphere
- 1800 stations
- 3106 discontinuities
- ~1159 GNSS sites
 - 1344 stations
 - 2938 discontinuities



DORIS



GNSS



SLR



VLBI



ITRF2020 Analysis Strategy

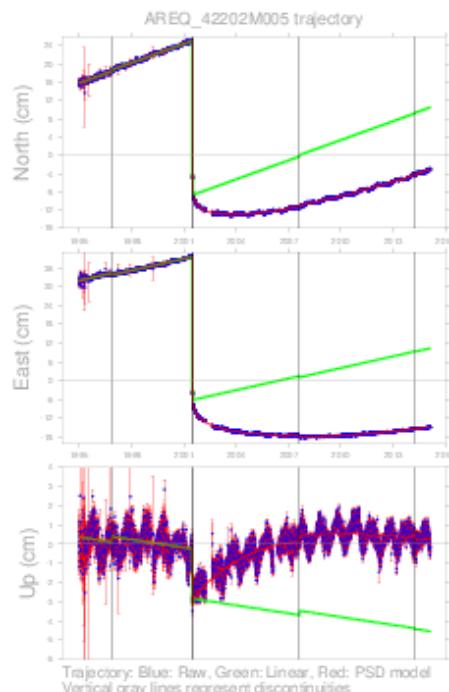
Input data: **Time series:**

- DORIS/IDS weekly
- GNSS/IGS daily
- SLR/ILRS weekly
- VLBI/IVS: Session-wise
- Local ties

Additional constraints **at colocation**

sites: Equality constraints for

- Station velocities
- Station seasonal signals



Time series analysis & stacking of the 4 technique time series **all together** + Modeling of nonlinear station motions:

- Periodic signals
- Post-Seismic Deformation

ITRF2020 Specifications:

Origin: SLR

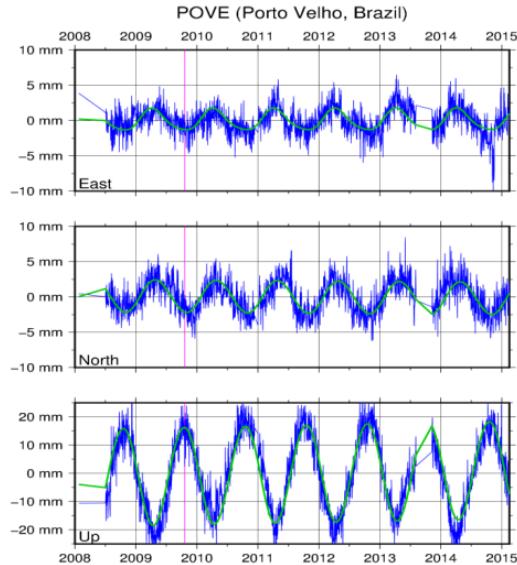
Scale: SLR & VLBI

Orientation: Alignment to ITRF2014

ITRF2020
 $\mathbf{X}, \dot{\mathbf{X}}, \delta\mathbf{X}_{PSD}, Seasonal Signals and EOPs$

ITRF2020 Innovation: Precisely Modeling nonlinear station motions

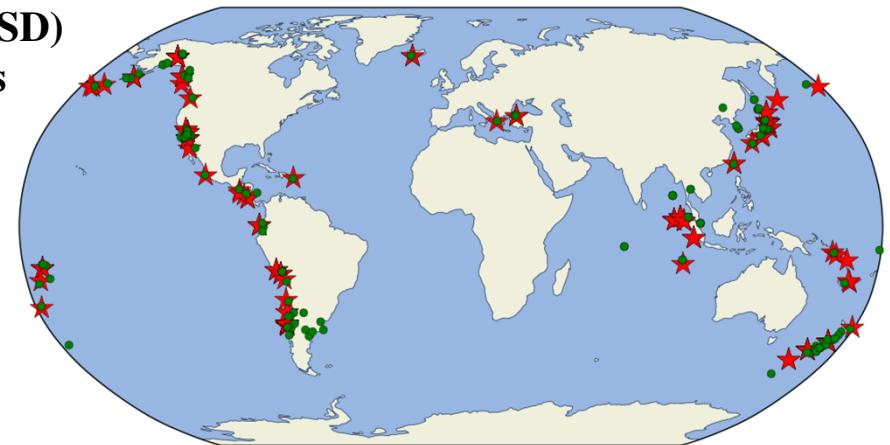
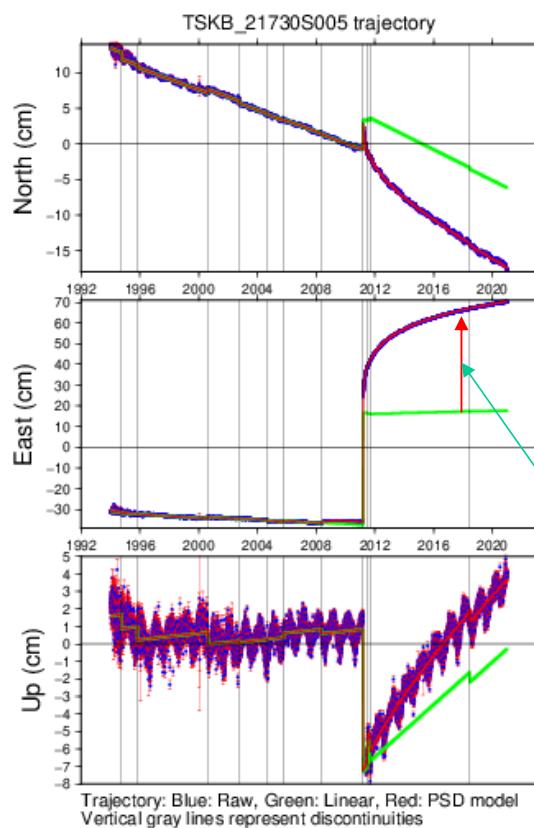
Impact of loading effects



Sine wave function

$$\Delta X_f(t) = \sum_{j=1}^{n_f} a_j^i \cos(\omega_j t) + b_j^i \sin(\omega_j t)$$

Post-Seismic Deformation (PSD) Impact of major earthquakes



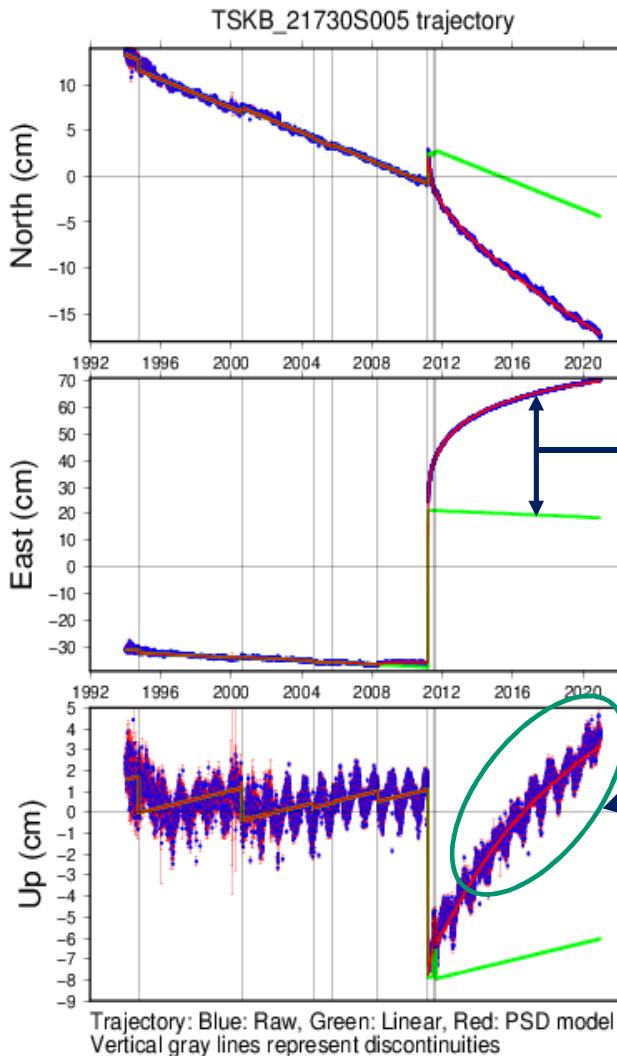
Red Stars: EQ Epicenters (65)
Green circles: ITRF2020 sites (118)

Refined PSD Parametric models:

1. Logarithmic Function
2. Exponential Function
3. Logarithmic + Exponential
4. Two Exponential Functions
5. Two Logarithmic Functions

$$\delta L(t) = \sum_{i=1}^{n^l} A_i^l \log\left(1 + \frac{t - t_i^l}{\tau_i^l}\right) + \sum_{i=1}^{n^e} A_i^e \left(1 - e^{-\frac{t - t_i^e}{\tau_i^e}}\right)$$

ITRF2020: Augmented Parametric Reference Frame



ITRF2020 Kinematic Model:

Linear part

Nonlinear part

$$X(t) = X(t_0) + \dot{X} \cdot (t - t_0) + \delta X_{PSD}(t) + \delta X_f(t)$$

\sum Post-Seismic Deformations (PSD)
Refined Parametric models

\sum Seasonal Signals, expressed in the CM-SLR frame

Station seasonal signals, geocenter motion and the reference frame definition

$$X(t) = X(t_0) + \dot{X} \cdot (t - t_0) + \delta X_{PSD}(t) + \delta X_f(t)$$

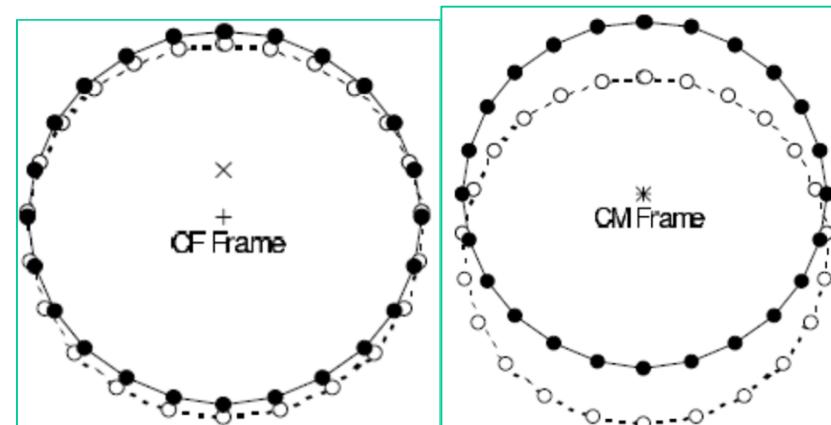
$$\delta X_f(t) = \sum_{i=1}^2 \begin{pmatrix} a_x^i \\ a_y^i \\ a_z^i \end{pmatrix} \cos(2i\pi \cdot t) + \begin{pmatrix} b_x^i \\ b_y^i \\ b_z^i \end{pmatrix} \sin(2i\pi \cdot t)$$

- δX_f : a & b are estimated in SLR CM-frame

$$X_{CM}(t) = X_{CF}(t) + \Delta X_G(t) \text{ (Geocenter motion)}$$

CM : Center of Mass Frame

CF : Center of Figure Frame



(Blewitt, 2003)

		Amplitude (mm)	Phase (Degrees)
<hr/>			
annual	X	1.23 +/- 0.16	-123.2 +/- 7.2
annual	Y	3.48 +/- 0.15	152.9 +/- 2.5
annual	Z	2.76 +/- 0.33	-139.5 +/- 6.8
<hr/>			
Semi-annual	X	0.49 +/- 0.15	107.2 +/- 18.1
Semi-annual	Y	0.22 +/- 0.15	1.6 +/- 39.0
Semi-annual	Z	1.19 +/- 0.33	30.5 +/- 15.5

Usage of ITRF2020 Seasonal Signals

The ITRF2020 kinematic model: $X(t) = X(t_0) + \dot{X} \cdot (t - t_0) + \delta X_{PSD}(t) + \delta X_f(t)$

Precise Orbit Determination : Use CM-based seasonal signals

Alignment of global solutions: Use either CM or CF seasonal signals

- ==> (1) Avoid aliasing the seasonal signals into the Helmert parameters &
(2) Seasonal signals will accurately be retained in the aligned solutions
1. If CM: translational motion common to all stations (i.e., seasonal geocenter motion) will be transferred to the aligned solutions
 2. If CF: the aligned solutions will be free from seasonal geocenter motion

Alignment of local or regional solutions:

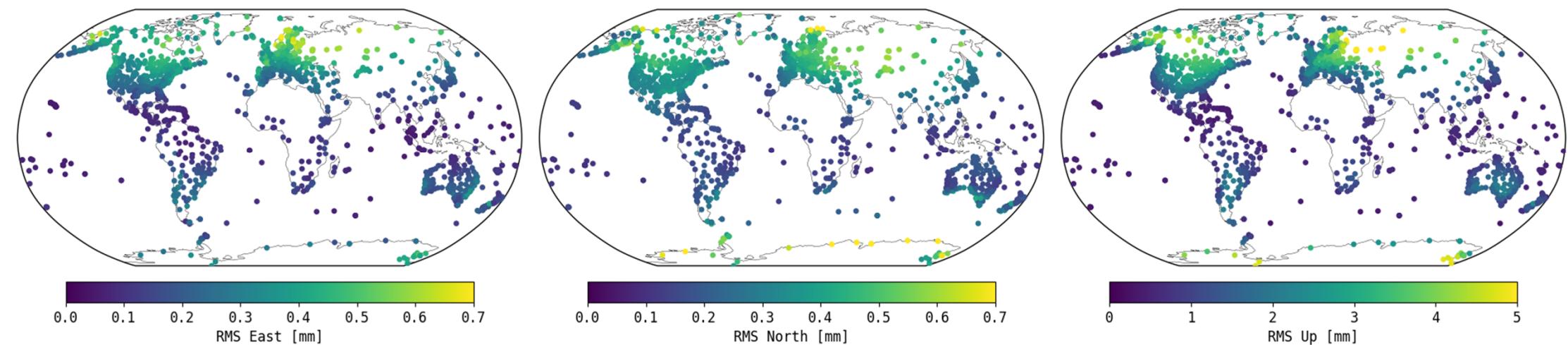
- CM or CF seasonal signals **can** be used depending on the user's need
- Common mode will be retained in the aligned solutions

ITRF Perspectives

- Long-term solution (station positions and velocities) will always be needed
- How to best represent the shape of the constantly deforming Earth?
- ITRF2020 is an augmented TRF: linear part + nonlinear part (PSD & Seasonal signals)
- What is left to be modeled?
- Aperiodic signals/displacements ? Expected magnitude?
 - Nonseasonal loading effects ?
 - High frequency atmospheric loading : up to 5 mm RMS in Up
 - Inter-annual hydrological loading : up to 5 mm RMS in Up
 - Residual displacements due to current ice melting for some locations few mm ?
 - ==> Geographically localized deformation (see illustrations next slides)
 - Other displacements?
 - Poro elastic, thermo elastic deformation, slow tectonic shifts?.. : few mm ?

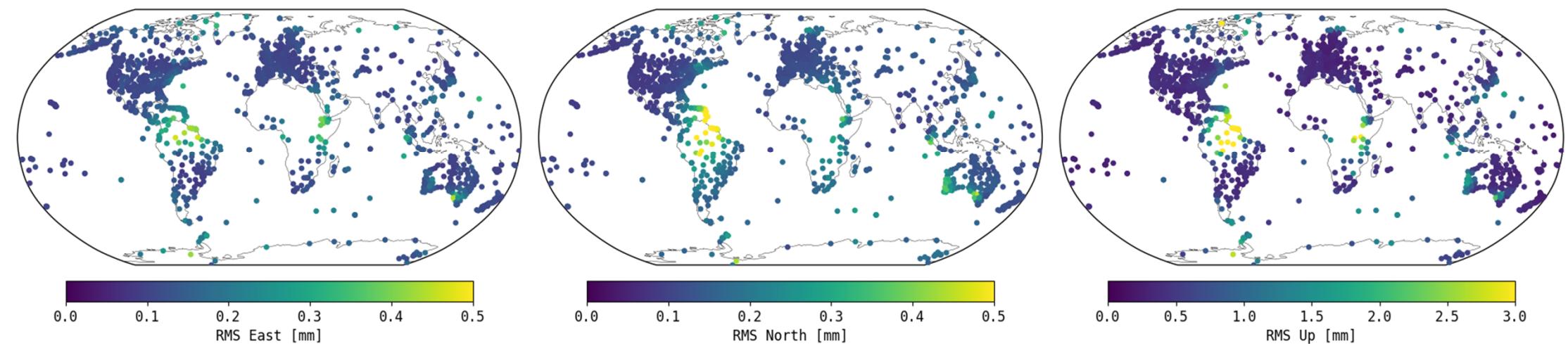
RMS of nonseasonal atmospheric loading displacements (ERA5 + IB from Boy 2021)

RMS of nonseasonal atmospheric loading displacements
(ERA5 + inverse barometer from Boy, 2021)



RMS of nonseasonal hydrological loading displacements (Combined GRACE solution, Gauer et al., 2022)

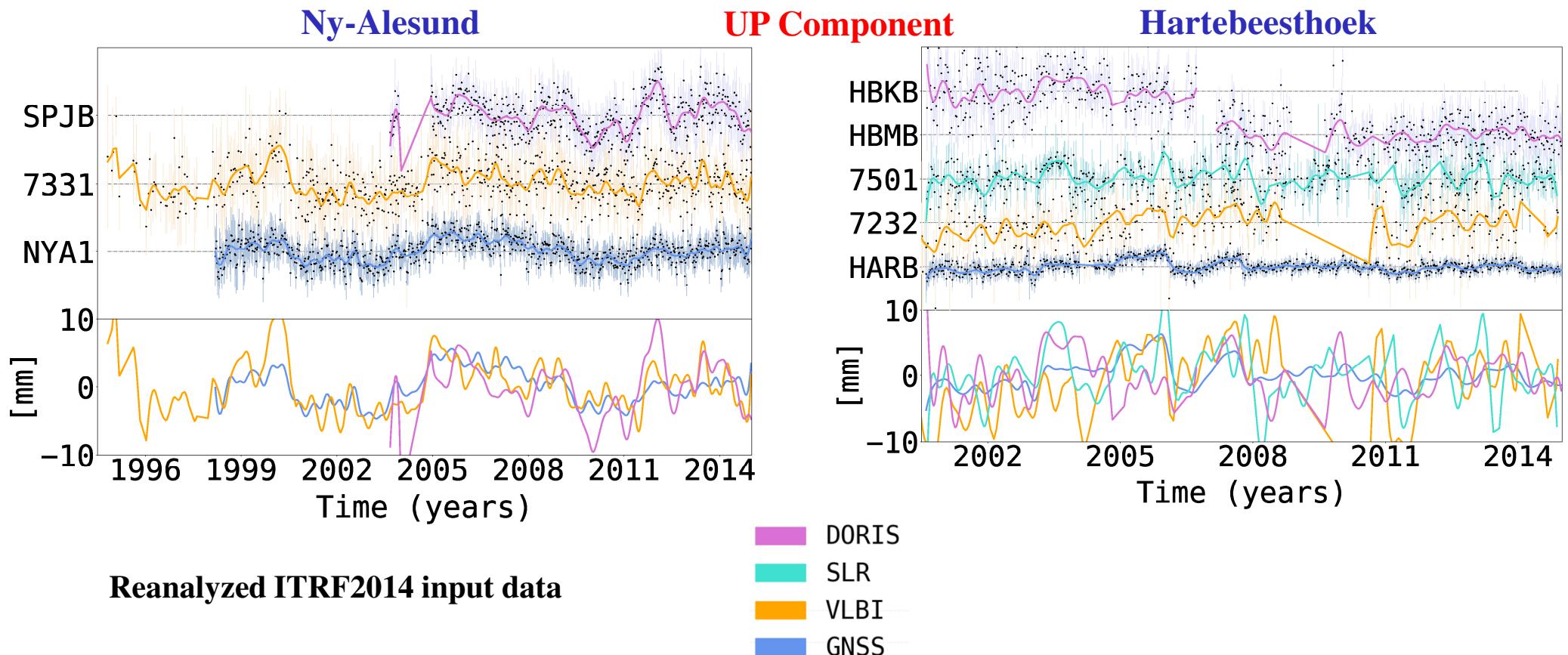
RMS of nonseasonal hydrological loading displacements
(combined GRACE solution from Gauer et al., 2022)



Are there common aperiodic displacements at ITRF co-location sites?

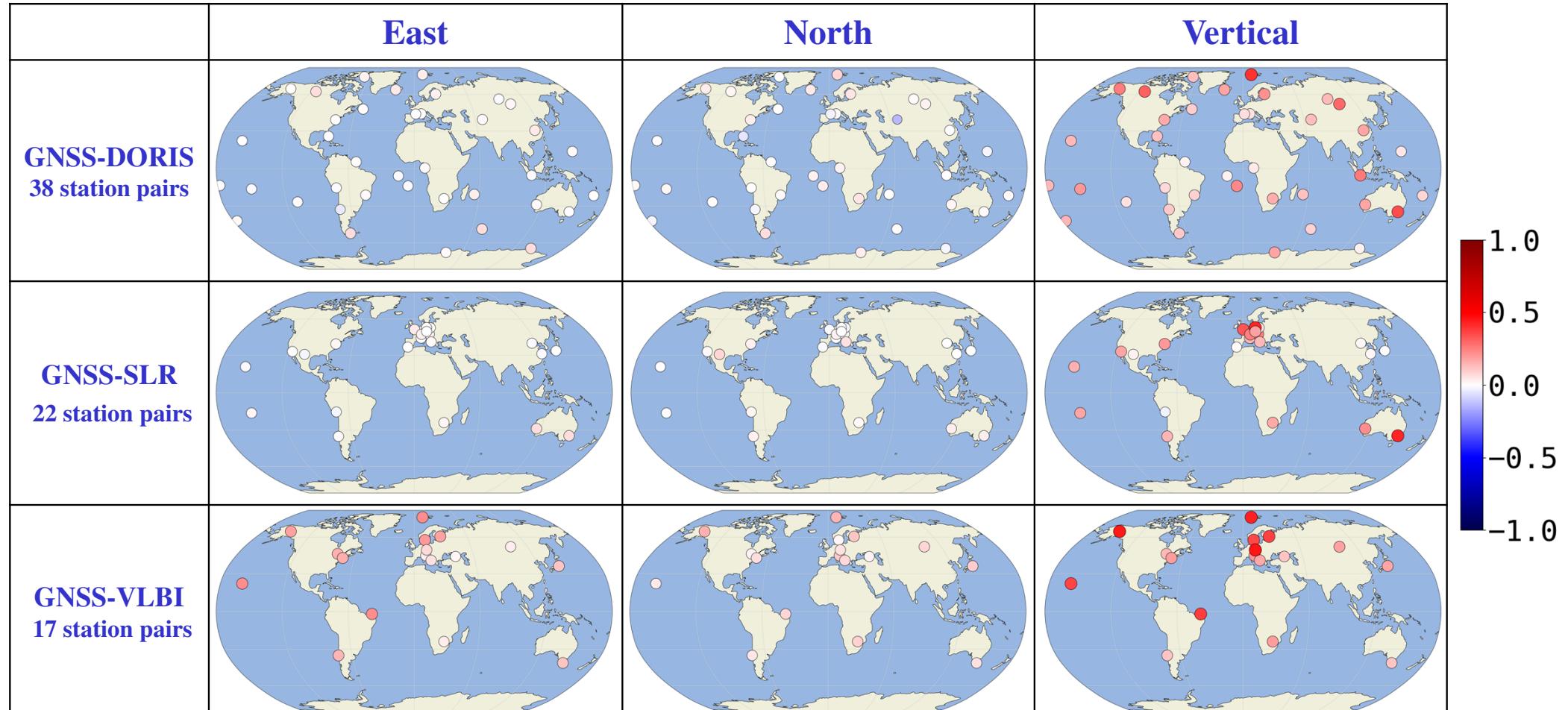
Are there common aperiodic displacements at ITRF co-location sites? (1/2)

After modeling and removing linear and periodic signals, what is left at:



Reanalyzed ITRF2014 input data

Are there common aperiodic displacements at ITRF co-location sites? (2/2)



Concordance correlation coefficients - Lin (1989)

Conclusion

- ITRF2020 is a step further in improving the ITRF determination;
- As an augmented TRF, ITRF2020 gives access to the quasi-instantaneous station positions, referred to the SLR CM, at the seasonal frequencies;
- Satisfies both operational geodesy and science applications, including Precise Orbit Determination;
- Some users are still reluctant to take full benefit of ITRF2020 seasonal signals
- ITRF2020 type of solution and its future updates will still be needed for a while!
- Limiting factors for detecting & combining “aperiodic signals” include:
 - Technique systematic errors;
 - Sparse networks;
 - limited observation density
 - Noise level;
 - ...
- Research on reference frames is still needed