



GNSS integrity

Challenges with Jamming & Spoofing in Civil Aviation
Main Focus on Flight Test Instrumentation

COMMERCIAL AIRCRAFT

Fabrice LAPEYRADE - October 2025

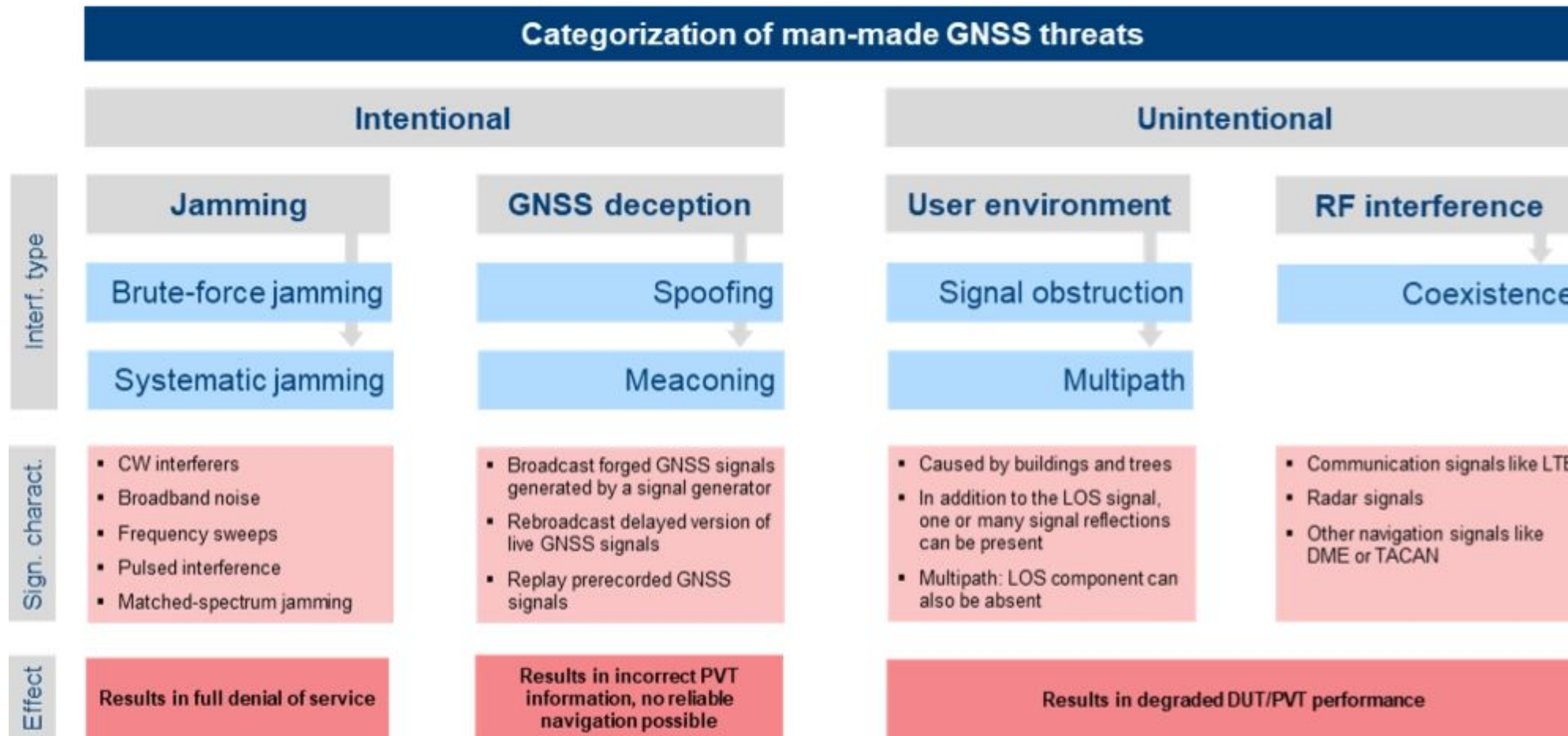
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Agenda

- Jamming and Spoofing definitions
- Aviation status
- Jamming/Spoofing dashboards
- Inertial-hybrid architecture
 - Avionics & Instrumentation (FTI)
- Jamming/Spoofing detection algorithms
- OSNMA
- CRPA antennas
- JammerTest event

Jamming and Spoofing definitions

In the past decades, most of GNSS threats in the real world were unintentional and/or limited in range!




Credits: [Testing GNSS receivers against jamming and spoofing attacks](#) - GPS World

Aviation status

Many areas are impacted and threats/zones **are evolving and growing over the time**:
Global Navigation Satellite System (GNSS) Outages and Alterations | EASA -
<https://www.easa.europa.eu/en/domains/air-operations/global-navigation-satellite-system-outages-and-alterations>

FIRs affected by jamming and spoofing

Although GNSS jamming and spoofing can be encountered anywhere in the world, according to the data collected so far, the mainly affected FIRs to date are the following:

powered by 

impacted FIRs in the last 7 days on 01/10/2025

src: ads-b data and reports

rank	reg...	ICAO	name	spoofing	reported
1	EUR	LTAA	ANKARA	*	
2	EUR	EPWW	WARSZAWA	*	
3	MID	ORBB	BAGHDAD	*	
4	ASIA	VYYF	YANGON	*	
5	EUR	ESAA	SWEDEN	*	
6	EUR	LBSR	SOFIA	*	

impacted FIRs in the last 30 days on 01/10/2025

src: ads-b data and reports

rank	reg...	ICAO	name	spoofing	reported
1	EUR	LTAA	ANKARA	*	
2	EUR	EPWW	WARSZAWA	*	
3	MID	ORBB	BAGHDAD	*	
4	ASIA	VYYF	YANGON	*	
5	EUR	ESAA	SWEDEN	*	
6	EUR	UUWV	MOSCOW	*	

Extract/overview
of long lists...

FIRs in EUR region

FIRs not in EUR region

FIR: Flight Information Region

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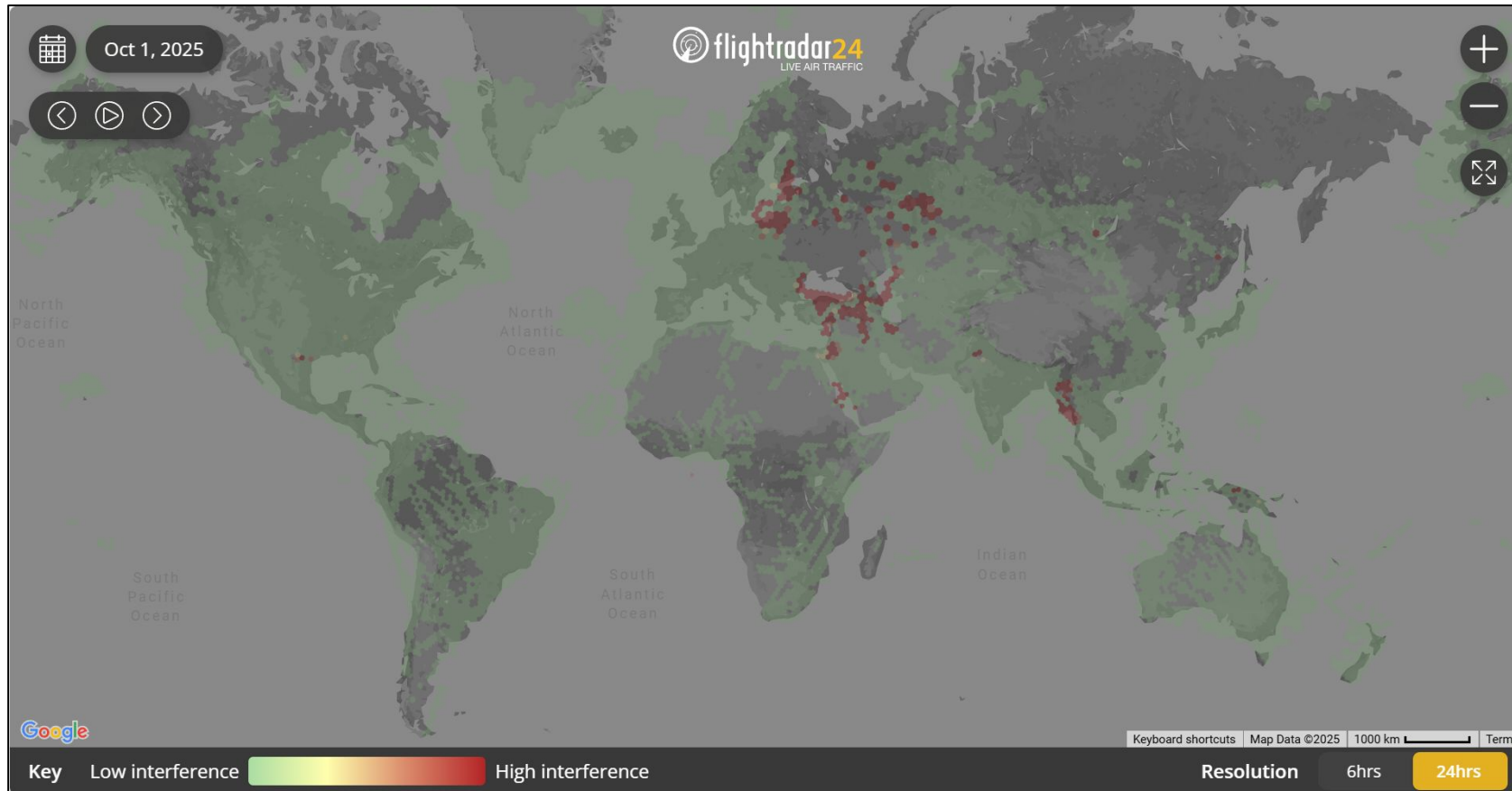
Jamming dashboard - principle & FlightRadar24

Several dashboards available that reflects Jamming information

- based on GNSS integrity indexes found in ADS-B (transponders) data from aircrafts overflying these areas

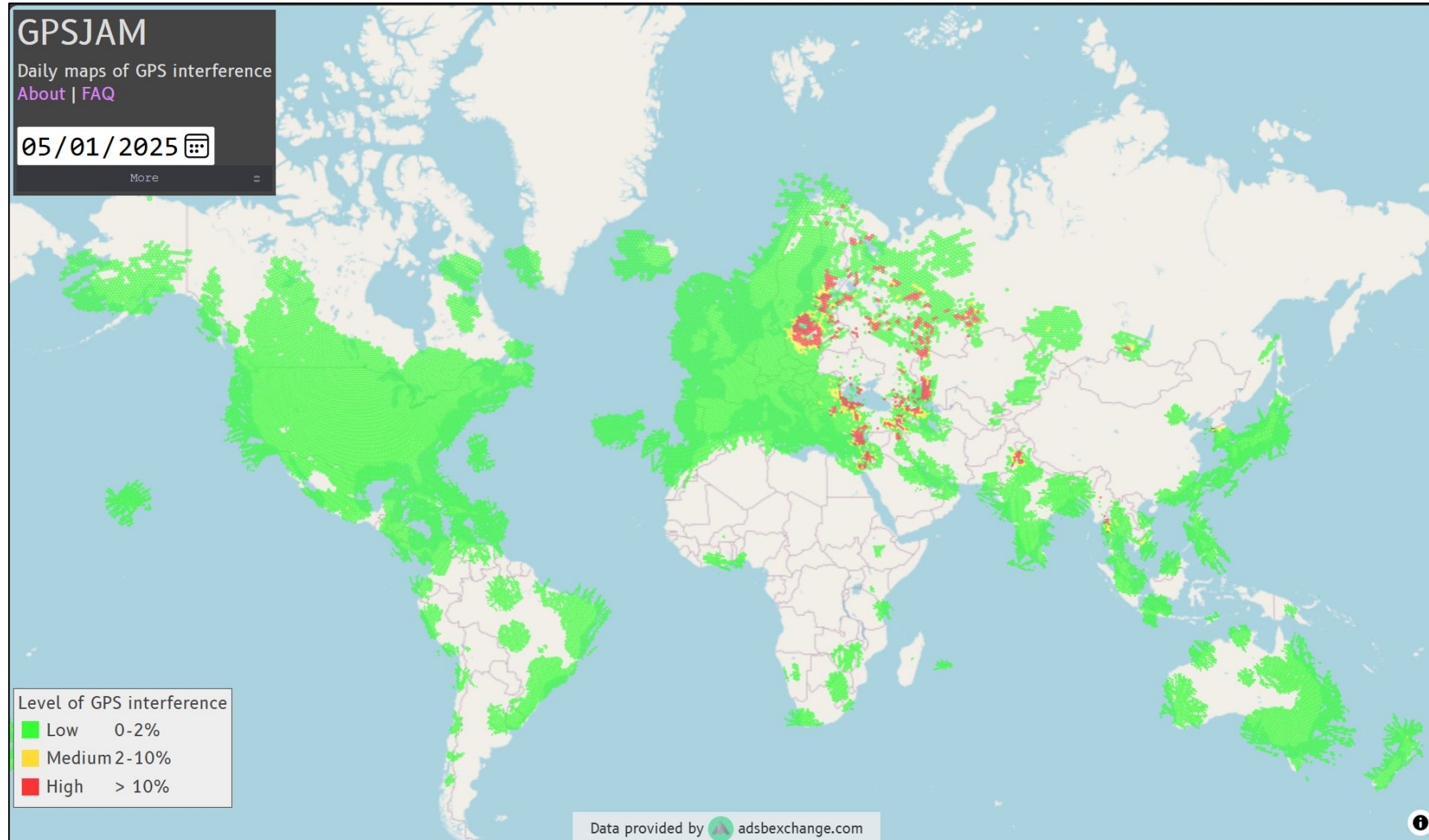
Examples:

GPS jamming & interference map | Flightradar24 - <https://www.flightradar24.com/data/gps-jamming>



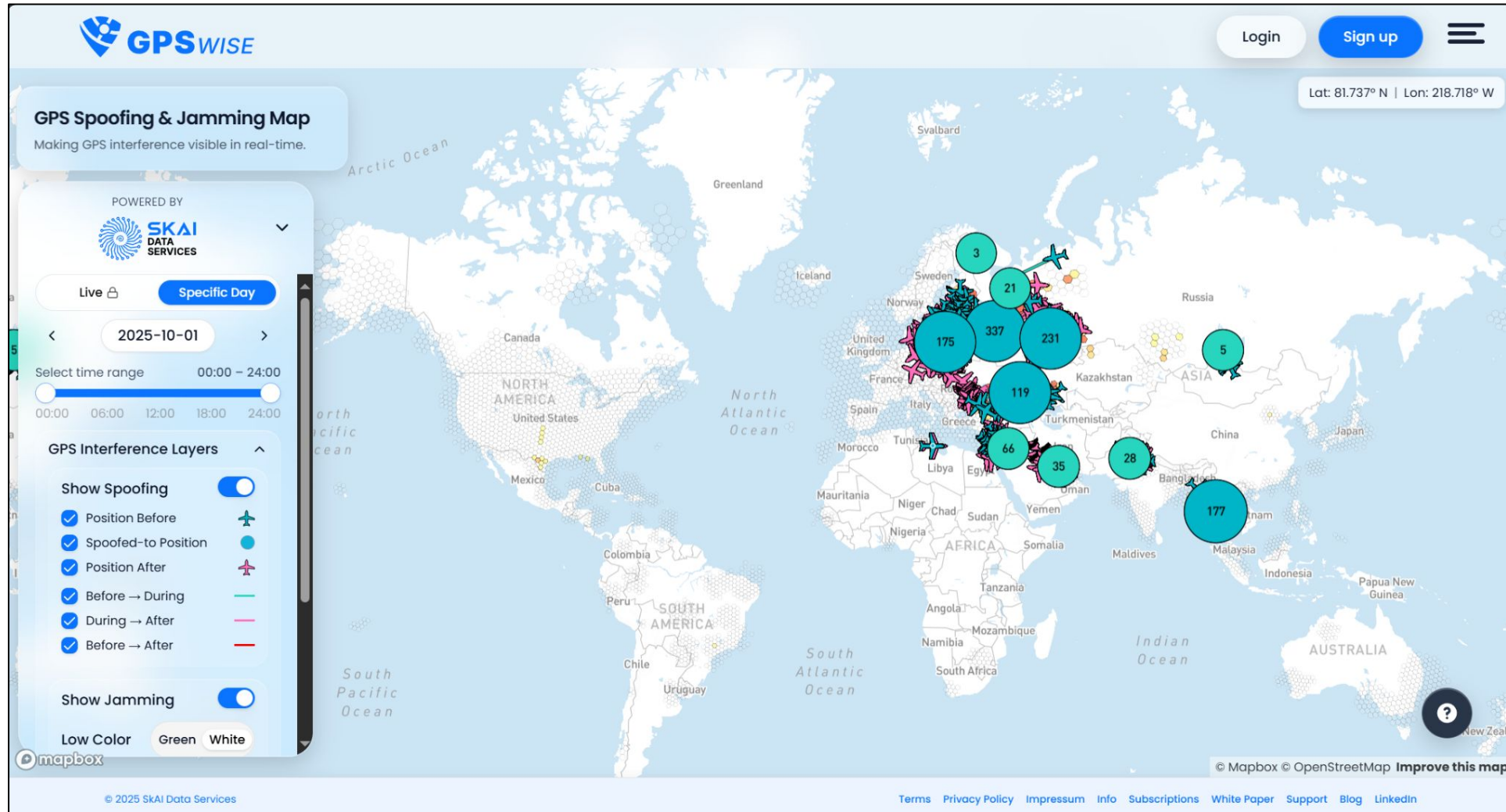
Jamming dashboard - GPSJam.org

<http://GPSJam.org>



Jamming dashboard - GPS wise

GPSwise | Live GPS Spoofing & Jamming Map - <https://gpswise.aero/>



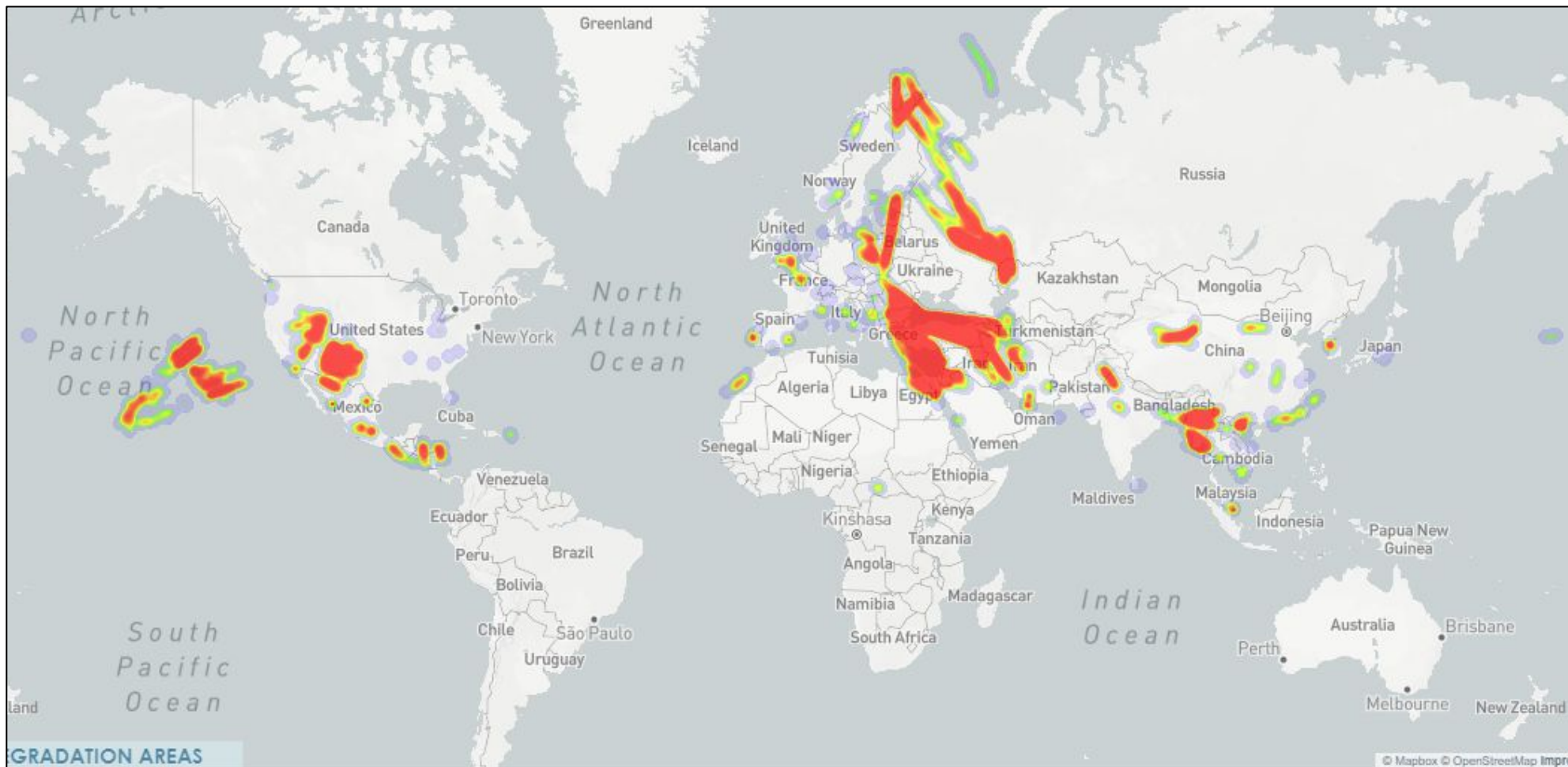
Jamming dashboard - Stanford university

GNSS Interference Detection using ADS-B - <https://waas-nas.stanford.edu/#/heatmap/>




Jamming dashboard - Airbus SkyWise

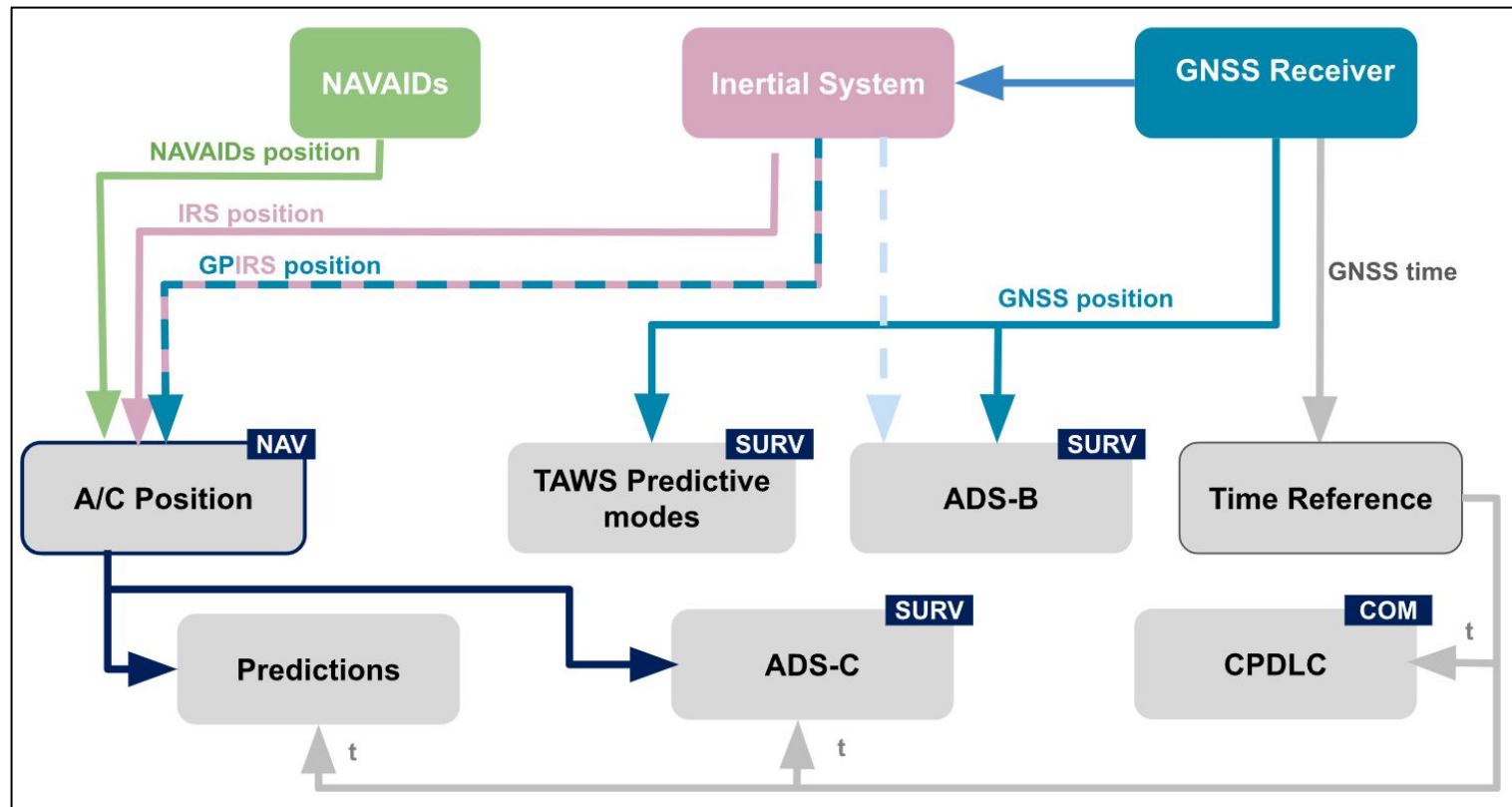
Airbus is also carefully monitoring the situation in direct link with our **customers** and all aviation stakeholders, including airworthiness authorities (like EASA)



Credits: Timo Warns (Airbus)
- ITSNT 2024

Inertial-hybrid architecture - Airbus avionics in “serial” aircrafts

- GNSS is used for Navigation (NAV), but also for Surveillance (SURV) and Communication (COM) functions
 - Navigation (NAV) position outputs rely mostly on **Inertial Reference System (IRS)**:
 - IRS tightly-coupled hybrid with GNSS
 - If GNSS lost then NAVAIDS & IRS
 - NAVAIDS: DME/DME or DME/VOR
 - If NAVAIDS lost then IRS-only
- 
- The diagram illustrates the relationship between NAVAIDS and the Inertial System. On the left, a green rounded rectangle is labeled 'NAVAIDS'. Below it, a green bracket is labeled 'NAVAIDS position'. On the right, a purple rounded rectangle is labeled 'Inertial System'. A blue arrow points from the right towards the 'Inertial System' box. Below the 'Inertial System' box, there are three vertical lines: a pink one, a blue one, and a light blue one.

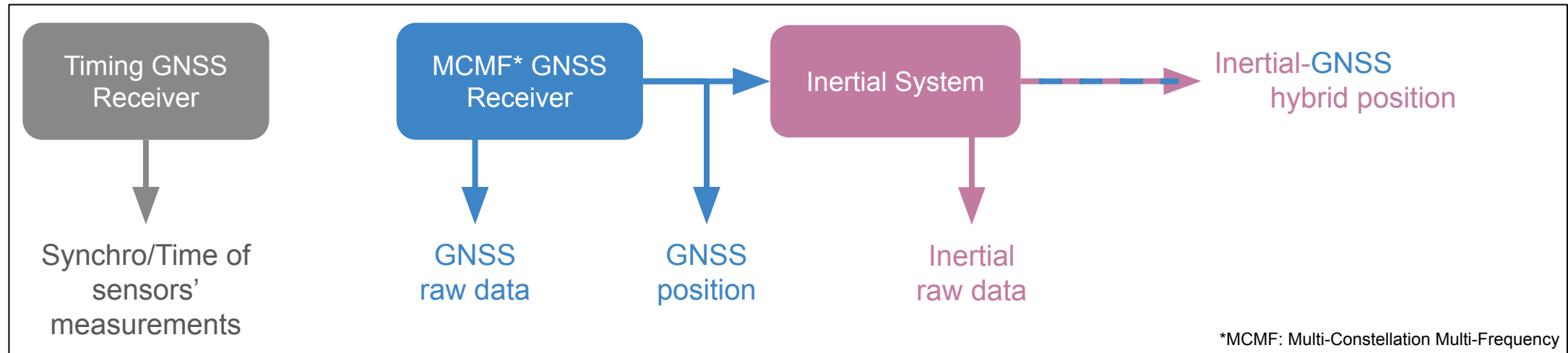


Acronyms:

A/C: Aircraft
ADS-B: Automatic Dependent Surveillance-Broadcast
ADS-C: Automatic Dependent Surveillance-Contract
CPDLC: Controller-Pilot Data Link Communication
DME: Distance Measuring Equipment
GPIRS: GPS and IRS hybridized computation
IRS: Inertial Reference System
NAVAIDs: Navigation Aids
TAWS: Terrain Awareness Warning System
VOR: Very High Frequency (VHF) Omnidirectional Ranging

Credits: Timo Warns (Airbus) - ITSNT 2024

Inertial-hybrid architecture - Flight Test Instrumentation (FTI)



- GNSS used for both Time synchronization and high-accuracy Reference Trajectory measurements
 - Position output available in a loosely-coupled hybrid between GNSS and Inertial system (with backward INS error correction)
 - Kalman filters designed to **detect outliers** by comparing 3D modelling inconsistencies between INS and GNSS
 - Originally created to filter out spurious results from multipath effects
 - Avoids using spoofed values as well
 - In case of outlier, standard deviations are growing accordingly to reflect related accuracy statistics
- ➔ **Need to detect Jamming & Spoofing and mitigate also at upper stages (GNSS receiver and/or antenna)**

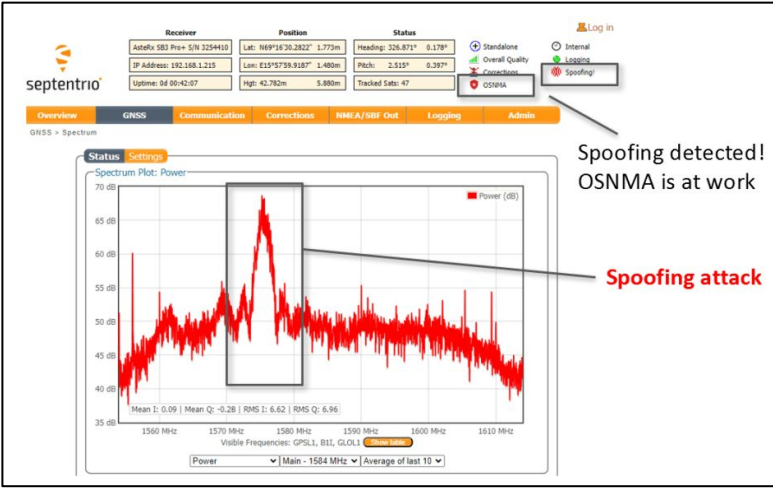
Jamming & Spoofing - FTI detection & mitigation

Solutions used for FTI for GNSS jamming/spoofing detection (and mitigation):



- Lack of open platforms for such algorithms
- Many useable from proprietary GNSS manufacturers' algorithms

Embedded in receivers such as: (non-exhaustive excerpt)




- Septentrio AIM+
- Javad
- Trimble RTX NMA



Satellites - Tracking Information?

ALL		GPS	GLONASS		Galileo	BeiDou	QZSS	NavIC	SBAS		MSS		
SV	Type	Elev. [°]	Azim. [°]	L1-C/No [dBHz]	L1	NMA	L2-C/No [dBHz]	L2	L5-C/No [dBHz]	L5	IODC	URA [m]	Type
5	GPS	75.80	149.90	48.1	CA		Authenticated	+CL	-	-	52	2	IIR-M
9	GPS	-45.00	0.00	-	CA			-	E/CM+CL	-	I+Q	-	-

Information?

QZSS	NavIC		SBAS	MSS
NMA	E5-C/No [dBHz]	E5	IODE	URA [m]
	51.5	Alt	39	3.12
	Authenticated		33	3.12
	44.3	Alt	39	3.12

Satellites	Sky Plot	Orientation	RTK Engines	RTPK	Weather Station						
Sys	Num	EI	Az	SNR				Track Time	Health	Used	Status
GPS - 2 / 0											
GPS	11	30	54	CA	P1	P2	L2C	L5	L1C		
GPS	11	30	54				33	46	33	00:02:17	Unhealthy SV (as follows from operational (=ephemeris) SV health)
GPS	29	77	264	32	27	27	36			00:02:05	Unhealthy SV (as follows from operational (=ephemeris) SV health)
GLO - 6 / 4											
GLO	7/5	13	354	CA	P1	P2	L2C	L3		00:00:21	SNR below specified minimum level
GLO	8/6	20	42	33	30	31	29			00:00:21	CA/L1 data used for position computation
GLO	15/0	68	250	32	35	31	29			00:03:23	CA/L1 data used for position computation
GLO	16/-1	30	324			34	37			00:02:56	L2C data used for position computation
GLO	17/4	61	242	38	35	29	32			00:03:23	CA/L1 data used for position computation
GLO	24/2	58	50	38	38	33	34			00:03:23	CA/L1 data used for position computation
GAL - 3 / 2											
GAL	21	23	306	E1	ABOC	ESB	ESA				
GAL	21	23	306				28			00:00:22	Measurements are not available
GAL	27	71	260	38	45	43	44			00:03:29	CA/L1 data used for position computation
GAL	34	58	68	28	44	43	41			00:03:30	P/L1 data used for position computation
BDS - 7 / 5											
BDS	8	52	86	B1	ABOC	B2(B)	B2A	B1C			
BDS	8	52	86	32		36				00:00:57	Measurements are not available
BDS	12	60	72	37		43				00:02:56	Measurements are not available
BDS	22	17	72	35	44	42	41	30		00:03:30	P/L1 data used for position computation
BDS	44	288	35	43	40	43	43	28		00:01:18	P/L1 data used for position computation
BDS	84	192	34	44	42	42	42	31		00:03:30	P/L1 data used for position computation
BDS	38	45	68	33	44	43	41	29		00:03:30	P/L1 data used for position computation
BDS	44	35	72	32	40	39	30	38		00:03:03	P/L1 data used for position computation
Legend: Spoofed (Orange), Jammed (Yellow), Spoofed and Jammed (Red)											
Satellites - Tracked: 18 / Used: 12 GPS - 2/0 GLO - 6/5 GAL - 3/2 BDS - 7/5 QZSS - 0/0 NavIC - 0/0 SBAS - 0/0 LBand - 0/0 GLCDMA - 0/0											

Galileo OSNMA tests

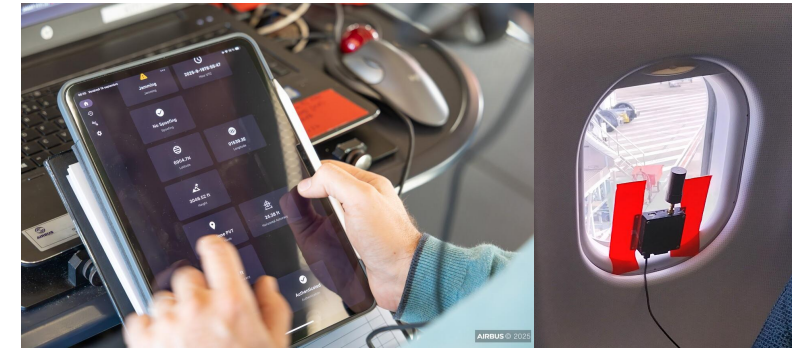
Galileo Open Service Navigation Message Authentication (OSNMA)

<https://www.gsc-europa.eu/galileo/services/galileo-open-service-navigation-message-authentication-osnma>

Fully operational since July 2025!

Used by Airbus in Flight Tests during JammerTest 2025:

- through COTS (Septentrio mosaic-x5) GNSS receiver as part of FTI
- JammerTest OSNMA results to be analysed



Interface on crew's EFB

COTS OSNMA
receiver & antenna

Another long-term mitigation: Authenticated SBAS

J&S Mitigation: CRPA technology for FTI

Use of Controlled Reception Pattern Antennas (CRPA) helps such J&S mitigation

Example of **Calian CR8894SXF+**

- Dual band GNSS L1/L2 signal support
- Supports eXtended Filtering+ (XF+) providing sharp out-of-band signal rejection
- Up to 20-40 dB null depth
- Serial interface provides state information and estimated jammer direction
- IP69K water proof housing
- Single RF feed/output - Compatible with standard GNSS receivers
- Very low power consumption (140 mA)
- Small, lightweight, and low-profile form factor makes it ideal for many uses
- Supports situational awareness, indicates CRPA state: jamming observed/mitigated, frequency, and direction

Used by Airbus in Flight Tests during JammerTest 2025:

→ JammerTest Calian CRPA results to be analysed



JammerTest 2025 - Airbus experiments

What is JammerTest event?

Intentional Jamming & Spoofing testings organized in Norway by TestNor (private company) liaising with local authorities
Various defined J&S scenarios broadcasted with a dedicated schedule in real environment

One Airbus development flight test aircraft participated to this 2025 edition.

Technologies exposed/tested during this flight test campaign:

- Various avionics computers (from Navigation but not only)
 - with several hardware & software standards/versions
- Galileo OSNMA based on COTS receiver
- CRPA 4 parts GNSS L1/L2 antenna from Calian, used for FTI
- GNSS RF L1& L5 IQ data recorded

Data analysis in progress, expected in coming months



Thank you

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